

Problème I 8pts

3pts ① $f_{m+1 \rightarrow m} = -K(x_m - x_{m+1})$, $f_{m-1 \rightarrow m} = -K(x_m - x_{m-1})$ 1pt 1pt

2^{ème} loi de Newton: 1pt

$$m\ddot{x}_m = -K(x_m - x_{m+1}) - K(x_m - x_{m-1})$$

$$\Rightarrow \ddot{x}_m + \omega^2 (2x_m - x_{m+1} - x_{m-1}) = 0, \quad \omega^2 = K/m$$

3pts ② $x_{m+1}(t) = F((m+1)a_0, t) \approx F(ma_0, t) + \frac{\partial F}{\partial x} a_0 + \frac{1}{2} \frac{\partial^2 F}{\partial x^2} a_0^2$ 1pt 1pt

$$x_{m-1}(t) = F((m-1)a_0, t) \approx F(ma_0, t) - \frac{\partial F}{\partial x} a_0 + \frac{1}{2} \frac{\partial^2 F}{\partial x^2} a_0^2$$

donc $\ddot{x}_m + \omega^2 (2x_m - x_{m-1} - x_{m+1}) = 0 \Rightarrow$

$$\frac{\partial^2 F(ma_0, t)}{\partial t^2} + \omega^2 \left(2F(ma_0, t) - 2F(ma_0, t) - \frac{\partial^2 F}{\partial x^2} a_0^2 \right) = 0$$

$$\boxed{\frac{\partial^2 F(x, t)}{\partial t^2} - \omega^2 a_0^2 \frac{\partial^2 F(x, t)}{\partial x^2} = 0}$$

← équation d'onde

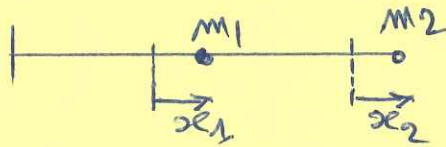
$$\frac{\partial^2 F(x, t)}{\partial x^2} - \frac{1}{\omega^2 a_0^2} \frac{\partial^2 F(x, t)}{\partial t^2} = 0$$

2pts ③ $\frac{1}{a_0^2 \omega^2} = \frac{1}{c^2} \Rightarrow c = a_0 \omega$, $a_0 = \frac{1}{K}$ où K est le nombre d'onde 1pt

c est la vitesse de phase 1pt

Problème II 12pt

2pt ①



$$\vec{F}_1 = -kx_1 \vec{u}_x - k(x_1 - x_2) \vec{u}_x$$

1pt

$$\vec{F}_2 = -k(x_2 - x_1) \vec{u}_x$$

1pt

2pt ②

$$\vec{F} = m\vec{a} \Rightarrow \begin{cases} \ddot{x}_1 = \omega_1^2 (x_2 - 2x_1) \\ \ddot{x}_2 = \omega_2^2 (x_1 - x_2) \end{cases}$$

1pt

1pt

$$\Rightarrow \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} + \underbrace{\begin{pmatrix} 2\omega_1^2 & -\omega_1^2 \\ -\omega_2^2 & \omega_2^2 \end{pmatrix}}_{=W} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

1pt

2pt ③

les valeurs propres λ^2 : $\begin{vmatrix} 2\omega^2 - \lambda^2 & -\omega^2 \\ -\omega^2 & \omega^2 - \lambda^2 \end{vmatrix} = 0$

1pt

$$\Rightarrow (2\omega^2 - \lambda^2)(\omega^2 - \lambda^2) - \omega^4 = 0$$

$$\lambda^4 - 3\omega^2 \lambda^2 + \omega^4 = 0^*$$

1pt

les pulsations propres $\omega_{\pm} = \lambda_{\pm} = \omega \sqrt{\frac{3 \pm \sqrt{5}}{2}}$

calcul: $\lambda_{\pm}^2 = \frac{3\omega^2 \pm \sqrt{9\omega^4 - 4\omega^4}}{2} = \omega^2 \left(\frac{3 \pm \sqrt{5}}{2} \right)$

2pt ④

vect. propres $\begin{pmatrix} a_{\pm} \\ b_{\pm} \end{pmatrix}$ tel que $\begin{pmatrix} 2\omega^2 - \lambda_{\pm}^2 & \omega^2 \\ -\omega^2 & \omega^2 - \lambda_{\pm}^2 \end{pmatrix} \begin{pmatrix} a_{\pm} \\ b_{\pm} \end{pmatrix} = 0$

$$\Rightarrow \begin{cases} (2\omega^2 - \lambda_{\pm}^2) a_{\pm} = \omega^2 b_{\pm} \\ -\omega^2 a_{\pm} = (\lambda_{\pm}^2 - \omega^2) b_{\pm} \end{cases}$$

$$\Rightarrow \frac{(2\omega^2 - \lambda_{\pm}^2) a_{\pm}}{\omega^2} = \frac{\omega^2 b_{\pm}}{\omega^2 - \lambda_{\pm}^2}$$

$$\boxed{\lambda_{\pm}^2} \quad (\omega^2 - \lambda_{\pm}^2) a_{\pm} = \lambda_{\pm}^2 b_{\pm} \Rightarrow \begin{cases} a_{\pm} = \lambda_{\pm}^2 \\ b_{\pm} = \omega^2 - \lambda_{\pm}^2 \end{cases} \Rightarrow \vec{V}_{\pm} = \begin{pmatrix} \lambda_{\pm}^2 \\ \omega^2 - \lambda_{\pm}^2 \end{pmatrix}$$

1pt

$$\vec{V} = \begin{pmatrix} \lambda_-^2 \\ \omega^2 - \lambda_-^2 \end{pmatrix} \text{ avec } \lambda_-^2 = \omega^2$$

3/3

⑤ Modes propres :

2pts

$$x_{\pm} = e^{i\omega_{\pm} t} \vec{V}_{\pm}$$

et leurs conjugués complexes

2pts

$$⑥ x(t) = ax_+ + bx_+^* + cx_- + dx_-^*$$

$$\Rightarrow x(0) = (a+b)x_+|_{t=0} + (c+d)x_-|_{t=0} = 0$$

$$\Rightarrow a = -b, c = -d$$

$$\begin{aligned} \dot{x}(0) &= (i\lambda_+ a - i\lambda_+ b)x_+|_{t=0} + (i\lambda_- c - i\lambda_- d)x_-|_{t=0} \\ \dot{x}(0) &= \begin{pmatrix} v_0 \\ -v_0 \end{pmatrix} \end{aligned}$$

$$\Rightarrow a = \frac{i v_0 (\omega^2 - \lambda_+^2)}{2\lambda_+ (\lambda_+^4 + (\omega^2 - \lambda_+^2)^2)}$$

$$c = \frac{i v_0 (\omega^2 - \lambda_-^2)}{2\lambda_- (\lambda_-^4 + (\omega^2 - \lambda_-^2)^2)}$$

$$\Rightarrow x(t) = 2ia (\sin(\lambda_+ t)) \vec{V}_+ + 2ic (\sin(\lambda_- t)) \vec{V}_-$$

Erreur dans la correction :

2 pts (2) $\vec{F} = m\vec{a} \Rightarrow \begin{cases} \ddot{x}_1 = \omega_1^2 (x_2 - 2x_1) & \text{4/4 0,5} \\ \ddot{x}_2 = \omega_2^2 (x_1 - x_2) & \text{4/4 0,5} \end{cases}, \omega_1^2 = \frac{k}{m_1}$

$\Rightarrow \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} + \underbrace{\begin{pmatrix} 2\omega_1^2 & -\omega_1^2 \\ -\omega_2^2 & \omega_2^2 \end{pmatrix}}_{= W \text{ 1pt}} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$